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NEW - Chapter 10 first discusses PID control in general and then presents two-degrees-of-freedom control systems—Presents a computational (MATLAB) method to determine system parameters so the system will have desired transient characteristics. NEW - Improved chapter on the design of control systems in state space (Chapter 12)—Treats pole placement and observer design.

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Designed for advanced engineering students who have had courses on differential equations, vector-matrix analysis, circuit analysis and mechanics, the fourth edition contains revisions and expansions that use MATLAB. The layout of the book covers the following: Laplace transforms, mathematical model

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Ogata's Modern Control Engineering, 5/e, offers the comprehensive coverage of continuous-time control systems that all senior students must have, including frequency response approach, root-locus approach, and state-space approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical arguments.

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on the classical control theory and modern control theory. A brief introduction of robust control theory is included in Chapter 10. Automatic control is essential in any field of engineering and science. Automatic control is an important and integral part of space-vehicle systems, robotic systems, mod-

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